

L19: April 6, 2017.

Housekeeping: Choose a final project (HW1 topics or any "projects" problem from back of chapter)

Pendulum homework due Tuesday -
written problems AND report on
computer model

Last time: Pendulum model

This time: Friction as damping for pendulum model

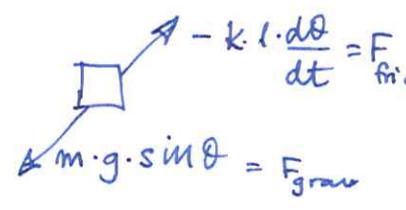
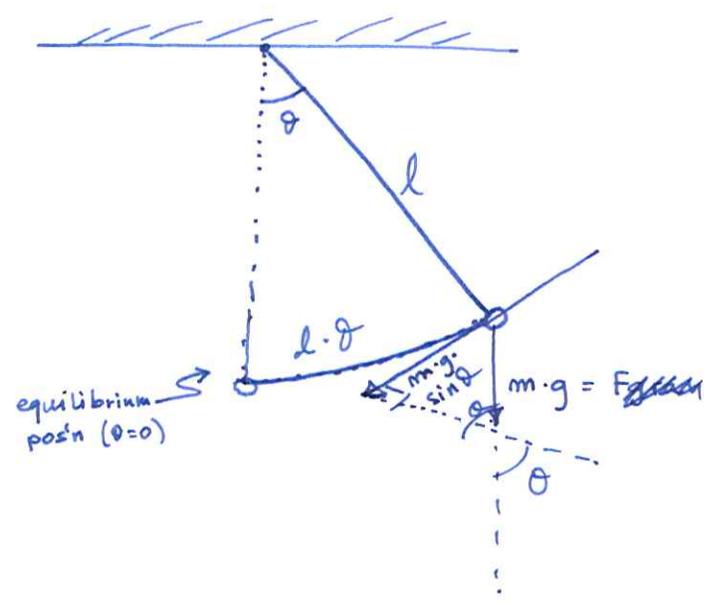
For a real pendulum, motion is damped by friction...

RECALL:

- Stokes' fric'n: very small object moving slowly through fluid; $F = -kv$
- Newtonian fric'n: larger objects moving faster through fluid; $F = \underbrace{0.5 C D A}_{= 0.65 \text{ for air at sea level.}} v^2$

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For the pendulum of a clock, we can safely use the simpler model of Stokes' friction — so we update the forces:



$$l \cdot m \cdot \frac{d^2 \theta}{dt^2} = F_{\text{net}} = F_{\text{grav}} + F_{\text{fric}}$$

$$l \cdot m \cdot \frac{d^2 \theta}{dt^2} = F_{\text{net}} = m g \sin \theta - k \frac{d\theta}{dt} \cdot l$$

$$\frac{d^2\theta}{dt^2} = \frac{g}{l} \sin\theta - \frac{k}{m} \frac{d\theta}{dt}$$

$$\frac{d^2\theta}{dt^2} + \frac{k}{m} \frac{d\theta}{dt} - \frac{g}{l} \sin\theta = 0$$

(p. 94 of text)

This governs pendulum motion subject to Stokes' friction.

$$\begin{cases} \theta(0) = \theta_0 & \text{initial angular displacement} \\ \left. \frac{d\theta}{dt} \right|_{t=0} = 0 & \text{initial velocity} \end{cases}$$

Assume $k = 6\pi \cdot D_r \cdot R$, $R = 0.01 \text{ mm}$

$$D_r \Big|_{\substack{40^\circ\text{F} \\ 1 \text{ ATM}}} = 3.60 \quad , \quad D_r \Big|_{\substack{70^\circ\text{F} \\ (\text{Std. Atm. pressure})}} = 3.82 \quad , \quad D_r \Big|_{\substack{60^\circ\text{F} \\ 1 \text{ ATM}}} = 3.75 \quad , \quad D_r \Big|_{\substack{50^\circ\text{F} \\ 1 \text{ ATM}}} = 3.68$$

$$(70, 3.82), (60, 3.75), (50, 3.68)$$

$$\frac{3.82 - 3.75}{70 - 60} \stackrel{?}{=} \frac{3.75 - 3.68}{60 - 50}$$

$$\frac{0.07}{10} \stackrel{?}{=} \frac{0.07}{10} \quad \checkmark$$